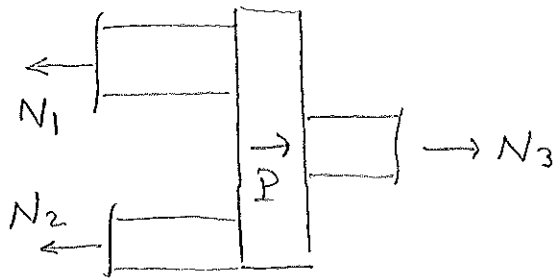


1.

$$\text{Jämvikt} \rightarrow: P - N_1 - N_2 + N_3 = 0 \quad (1)$$



Konstitutiva samband

$$N_1 = \frac{E \cdot (2A)}{L} \delta_1 \quad N_2 = \frac{E \cdot (3/2 A)}{L} \delta_2 \quad N_3 = \frac{EA}{2L/3} \delta_3 \quad (2)$$

Kompatibilitet

$$\delta_1 = \delta_2 \quad \delta_1 + \delta_3 = 0 \Rightarrow \delta_1 = \delta_2 = -\delta_3 \quad (3)$$

$$(2) \text{ i } (3) \Rightarrow \frac{N_1}{2} = \frac{2}{3} N_2 = -\frac{2}{3} N_3 \Rightarrow N_1 = \frac{4}{3} N_2 = -\frac{4}{3} N_3$$

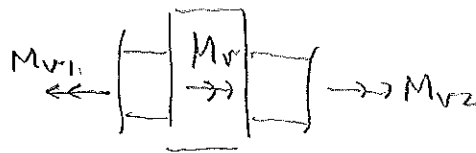
insatt i (1) \Rightarrow

$$P - \frac{4}{3} N_2 - N_2 - N_2 = 0 \Rightarrow \boxed{N_2 = \frac{3}{10} P} \quad \boxed{N_1 = \frac{2}{5} P}$$

$$\boxed{N_3 = -\frac{3}{10} P}$$

$$\text{Förflytt. av stel skruva} = \delta_1 = \delta_2 = \frac{N_1 \cdot L}{E \cdot 2A} = \frac{PL}{5 \cdot EA} = 1 \text{ [mm]}$$

(2)

Jämvikt

$$\rightarrow: M_v - M_{v1} + M_{v2} = 0 \quad (1)$$

Konstitutiva samband

$$\Delta\varphi_1 = \frac{M_{v1} \cdot L}{G K_1}$$

$$\Delta\varphi_2 = \frac{M_{v2} L}{G K_2}$$

$$\text{där } K_1 = \frac{\pi}{2} a^4$$

$$K_2 = \frac{\pi}{2} (a^4 - (a/2)^4) = \frac{\pi a^4 \cdot 15}{32}$$

(2)

Kompatibilitet

$$\Delta\varphi_1 + \Delta\varphi_2 = 0 \Rightarrow \frac{M_{v1}}{K_1} + \frac{M_{v2}}{K_2} = 0 \Rightarrow M_{v2} = -\frac{K_2}{K_1} M_{v1} =$$

$$= -\frac{15/32}{1/2} M_{v1} = -\frac{15}{16} M_{v1} \quad (3)$$

$$(3) \text{ i } (1) \Rightarrow M_v - M_{v1} - \frac{15}{16} M_{v1} = 0 \Rightarrow \boxed{M_{v1} = \frac{16}{31} M_v}$$

$$\boxed{M_{v2} = -\frac{15}{31} M_v}$$

Största vridskjuvspänningen

$$\tau_{\max,1} = \frac{2 \cdot M_{v1} \cdot a}{\pi \cdot a^4} = \frac{32 \cdot M_v}{31 \cdot \pi \cdot a^3} \approx 65,7 \text{ [MPa]}$$

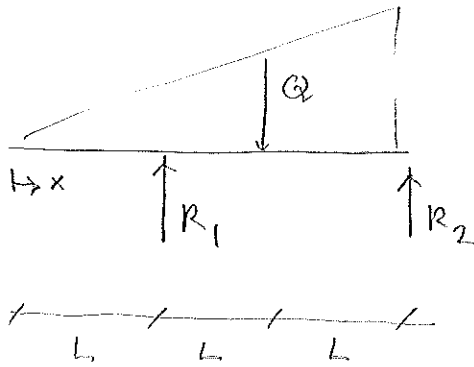
$$\tau_{\max,2} = \frac{2 M_{v2} \cdot a}{\pi \cdot (a^4 - (a/2)^4)} = -\frac{30 \cdot M_v}{31 \cdot \pi \cdot 1/16 \cdot a^3} = -\frac{480 \cdot M_v}{31 \pi a^3} =$$

$$\approx -65,7 \text{ [MPa]}$$

Max vridskjuvspänning $\approx 65,7 \text{ MPa} //$

3 Jämvidet

$$Q = \int_0^{3L} q(x) dx$$



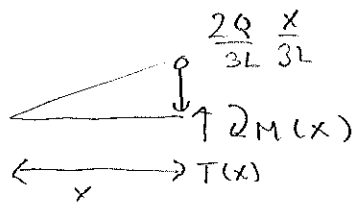
$$\uparrow: R_1 + R_2 - Q = 0$$

$$\uparrow: QL - R_2 \cdot 2L = 0$$

$$\Rightarrow R_1 = R_2 = Q/2$$

Tränkraft $T(x)$

$0 < x < L$

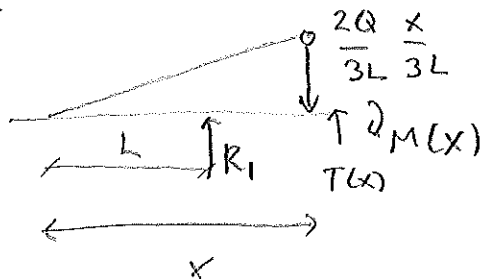


$$\uparrow: T(x) - \frac{Q}{3L} \frac{x^2}{3L} = 0$$

$$\Rightarrow T(x) = \frac{Qx^2}{9L^2}$$

$$T(0) = 0, T(L^-) = \frac{Q}{9}$$

$L < x < 3L$



$$\uparrow: T(x) - \frac{Qx^2}{9L^2} + \frac{Q}{2} = 0$$

$$\Rightarrow T(x) = \frac{Qx^2}{9L^2} - \frac{Q}{2}$$

$$T(L^+) = -\frac{7}{18} Q$$

$$T(3L) = \frac{Q}{2}$$

b) Lokala min och max av $T(x)$ där $T'(x) = 0$

$$\Rightarrow x = 0 \Rightarrow T = 0$$

Därför fås max i ändpunkter på intervall
dvs $T(0)$, $T(L)$ eller $T(3L)$

$$\Rightarrow \max |T(x)| = \frac{Q}{2}$$

Böjskjuvspänning

$$\tau = \frac{S_{Ax} \cdot T}{I \cdot b}$$

där $S_{Ax} = 5t \cdot t \cdot \left(\frac{5t}{2} + \frac{t}{2} \right) = 15t^3$

$$I = \frac{t \cdot (5t)^3}{12} + 2 \cdot \left[\frac{5t \cdot t^3}{12} + (5t \cdot t) \cdot \left(\frac{t}{2} + \frac{5t}{2} \right)^2 \right] =$$
$$= \frac{405}{4} \cdot t^4$$

$$b = t$$

$$\Rightarrow \tau_{max} = \frac{15t^3 \cdot \frac{1}{2} Q}{\frac{405}{4} t^4 \cdot t} = \frac{Q}{t^3} \frac{2}{27} //$$

4) Elastiska linjens ekv

$$EI w^{IV}(x) = q(x) = q_0 \sin\left(\frac{2\pi x}{L}\right)$$

$$\Rightarrow EI w^{III}(x) = -q_0 \frac{L}{2\pi} \cos\left(\frac{2\pi x}{L}\right) + C_1 \Rightarrow$$

$$\Rightarrow EI w''(x) = -q_0 \left(\frac{L}{2\pi}\right)^2 \sin\left(\frac{2\pi x}{L}\right) + C_1 x + C_2 \Rightarrow$$

$$\Rightarrow EI w'(x) = q_0 \left(\frac{L}{2\pi}\right)^3 \cos\left(\frac{2\pi x}{L}\right) + C_1 \frac{x^2}{2} + C_2 x + C_3 \Rightarrow$$

$$\Rightarrow EI w(x) = q_0 \left(\frac{L}{2\pi}\right)^4 \sin\left(\frac{2\pi x}{L}\right) + C_1 \frac{x^3}{6} + C_2 \frac{x^2}{2} + C_3 x + C_4$$

Randvillkor.

$$\begin{cases} w(0) = 0 \\ w'(0) = 0 \end{cases} \Rightarrow \begin{cases} C_4 = 0 \\ q_0 \left(\frac{L}{2\pi}\right)^3 + C_3 = 0 \Rightarrow C_3 = -q_0 \left(\frac{L}{2\pi}\right)^3 \end{cases}$$

$$\begin{cases} M(L) = 0 \Rightarrow w''(L) = 0 \Rightarrow C_1 L + C_2 = 0 \Rightarrow C_2 = -C_1 \cdot L \\ k w(L) = \underbrace{-T(L)}_{-EI w'''(L)} = EI w'''(L) \end{cases}$$

$$\Rightarrow \frac{k}{EI} \left[C_1 \frac{L^3}{6} - C_1 L \cdot \frac{L^2}{2} - q_0 \left(\frac{L}{2\pi}\right)^3 \cdot L \right] = -q_0 \frac{L}{2\pi} + C_1 \Rightarrow$$

$$\Rightarrow C_1 \left[-\frac{1}{3} \alpha - 1 \right] = -q_0 \frac{L}{2\pi} + \frac{\alpha}{(2\pi)^3} L q_0 \Rightarrow$$

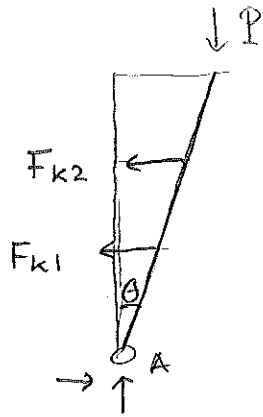
$$\Rightarrow C_1 = \frac{q_0 L \left(\frac{1}{2\pi} - \frac{\alpha}{(2\pi)^3} \right)}{\frac{\alpha}{3} + 1} = \frac{q_0 \cdot L \cdot 3 \cdot (4\pi^2 - \alpha)}{8 \cdot \pi^3 \cdot (\alpha + 3)}$$

$$\Rightarrow w(x) = q_0 \left(\frac{L}{2\pi}\right)^4 \sin\left(\frac{2\pi x}{L}\right) + \frac{3 q_0 L}{8 \pi^3} \frac{4\pi^2 - \alpha}{\alpha + 3} \left(\frac{x^3}{6} - \frac{x^2 L}{2} \right) - q_0 \left(\frac{L}{2\pi}\right)^3 x$$

$$\Rightarrow w(x) = \frac{1}{EI} \left[\frac{q_0 L^3}{2\pi^3} \frac{(\alpha - 4\pi^2)}{(3 - \alpha)} \left[\frac{x^3}{6} - \frac{x^2 L}{2} \right] - q_0 \left(\frac{L}{2\pi}\right)^3 x \right]$$

5.

Jämvikt i deformerat läge:



$$F_{k1} = k \cdot \theta L$$

$$F_{k2} = k \theta 2L$$

$$\vec{A}: P \cdot \theta 3L - F_{k1} \cdot L - F_{k2} 2L = 0$$

$$\Rightarrow P \cdot \theta \cdot 3L - k \theta L^2 - k 4 \theta L^2 = 0$$

$$\Rightarrow \theta = 0 \text{ eller } \frac{P \cdot 3L - 5kL^2}{kr} = 0 \Rightarrow \frac{P}{kr} = \frac{5kL}{3} //$$