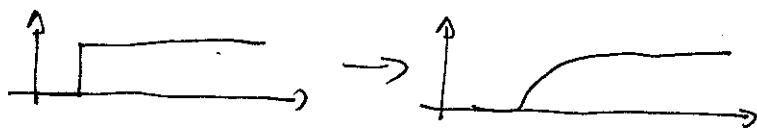


Solutions to the exam ESS101

2007 -04 -12

1. a) A nonparametric method for identification, where you study impulse responses or step responses

Example:



- b) Discretize the spacial variable

- c) High accuracy, but sensitive to disturbances which are modelled (or captured) in the model.

- d) On Kronecker form

$$N = \begin{bmatrix} 0 & 0 & 0 \\ 2 & 0 & 0 \\ 0 & 3 & 0 \end{bmatrix} \quad \text{index } = k \quad N^k = 0 \text{ gives } N^3 = 0 \Rightarrow k = 3 \quad \underline{\text{index } = 3}$$

- e) In a static system the output depends directly on the input (no memory), while in a dynamic system the output depends on old input signals and output signals.

2.

$$a) E\{y^2(t)\} = E\{b_1 + b_2 u(t-1) + c(b)\}^2 =$$

$$= b_1^2 + b_2^2 + \lambda$$

$$E\{y(t)u(t-1)\} = b_1,$$

$$E\{(y - y_m)^2\} = b_1^2 + b_2^2 + \lambda - 2b_1 b_2 + b_2^2 + \lambda$$

$$= (b_1 - b_2)^2 + b_2^2 + 2\lambda$$

$$\min \text{ on } \underline{\underline{b = b_1}}$$

$$b) E\{y^2(t)\} = b_1^2 E\{u^2(t-1)\} + 2b_1 b_2 E\{u(t-1)u(t-2)\}$$

$$+ b_2^2 E\{u^2(t-2)\} + \lambda = b_1^2 + b_1 b_2 + b_2^2 + \lambda$$

$$E\{y(t)u(t-1)\} = b_1 + 0.5 b_2$$

$$E\{(y - y_m)^2\} = b_1^2 + b_1 b_2 + b_2^2 + \lambda - 2b_1 b_2 + \cancel{b_2^2} + \lambda$$

$$= b_1^2 + b_1 b_2 + b_2^2 + 2\lambda - 2b_1 b_2 - b_2^2 + b_2^2$$

$$- 2b_1 - b_2 + 2b = 0$$

$$\underline{\underline{b = \frac{2b_2 + b_1}{2}}}$$

$$u_2 = R i_2$$

3. a)

$$\dot{i}_2 = \frac{N_1}{N_2} \dot{i}_1 - \frac{N_1}{N_2} i_m = \frac{N_1}{N_2} \dot{i}_1 - \frac{N_1}{N_2} \varphi_m(B)$$

$$\dot{B} = \frac{\dot{\phi}}{A} = \frac{1}{N_2 A} u_2 = \frac{R}{N_2 A} \dot{i}_2 = \underline{\underline{\frac{R}{N_2 A} \left(\frac{N_1}{N_2} \dot{i}_1 - \frac{N_1}{N_2} \varphi_m(B) \right)}}$$

$$\dot{i}_2 = \frac{N_1}{N_2} \dot{i}_1 - \frac{N_1}{N_2} \varphi_m(B)$$

b)

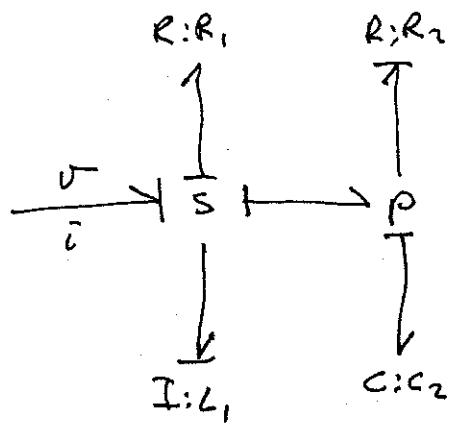
Linearize

$$\Delta \dot{B} = - \frac{RN_1}{AN_2^2} \Delta B + \frac{RN_1}{AN_2^2} \Delta \dot{i}_1$$

$$\Delta \dot{i}_2 = - \frac{N_1}{N_2} \Delta B + \frac{N_1}{N_2} \Delta \dot{i}_1$$

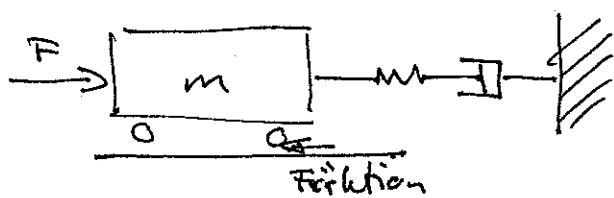
4

a)



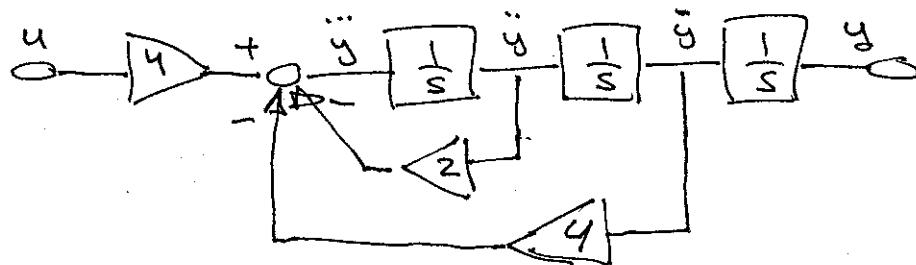
v input signal \rightarrow causality ok.

b)



5.

a)



b)

$$\dot{x} = -3x$$

$$x(t+h) = x(t) - 3h x(t+h)$$

$$x(t+h) = \frac{1}{1-3h} x(t)$$

stable if:

$$\left| \frac{1}{1-3h} \right| < 1$$

$$|1-3h| > 1$$

$$1-3h < -1$$

$$-3h < -2$$

$$h > \frac{2}{3}$$

 $\underline{\underline{}}$